



Human Detection using Morphological Analysis and Image Parsing Technique

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Introduction

- Most searched content.
- Use to bring out various émotions and myriade of human feelings and moments.
- Images in the web are stored in the form of table or tables.
- Image search accuracy is fairly low.
- First step in many surveillance systems.

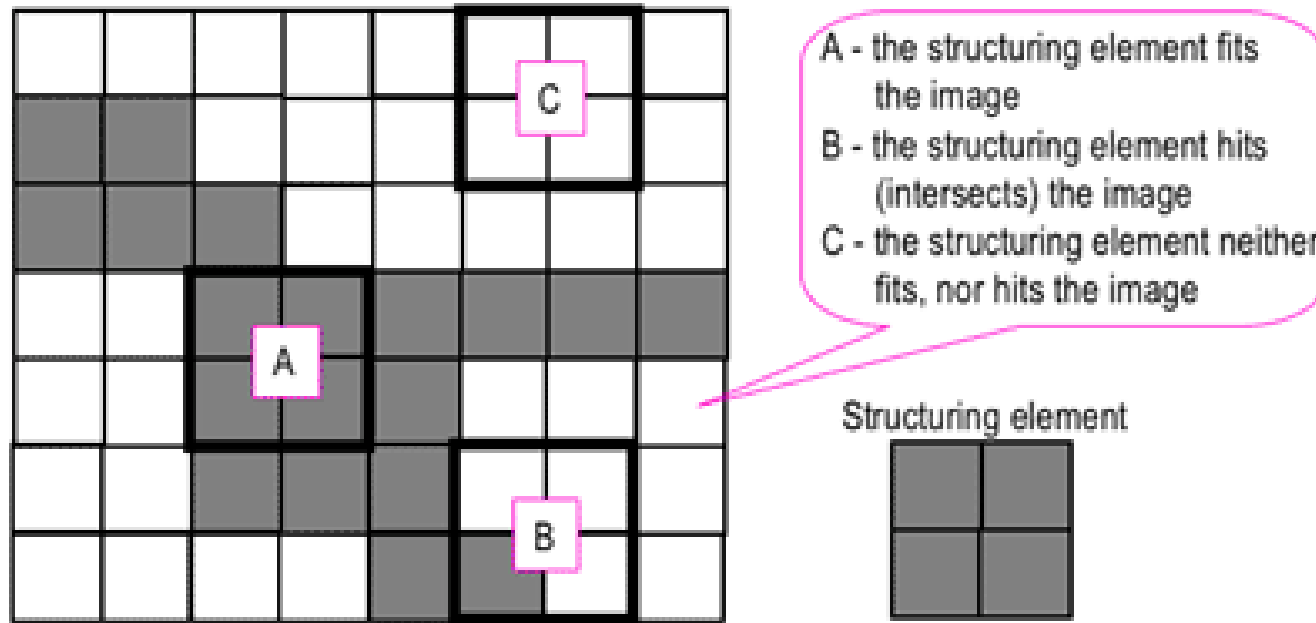
Overview of Work

- Two steps are usually followed for the searching of images
 - Query Building
Formation of the search query for searching the images.
 - Information Retrieval
Displaying of the images based on the matched results.
- Here using **Morphological Analysis** and **Parsing** of a given image, we tend to bring out the human present in the picture.

Morphological Analysis

- Identification, analysis, and description of the structure of the smallest unit of words
- Theory and technique for the analysis and processing of geometric structures
 - *Based on set theory, lattice theory, topology, and random functions*
 - *Extract image components useful in the representation and description of region shape such as boundaries, skeletons, and convex hull*
 - *Input in the form of images, output in the form of attributes extracted from those images*
 - *Attempt to extract the meaning of the images*

Morphological techniques probe an image with a small shape or template called a **structuring element**.

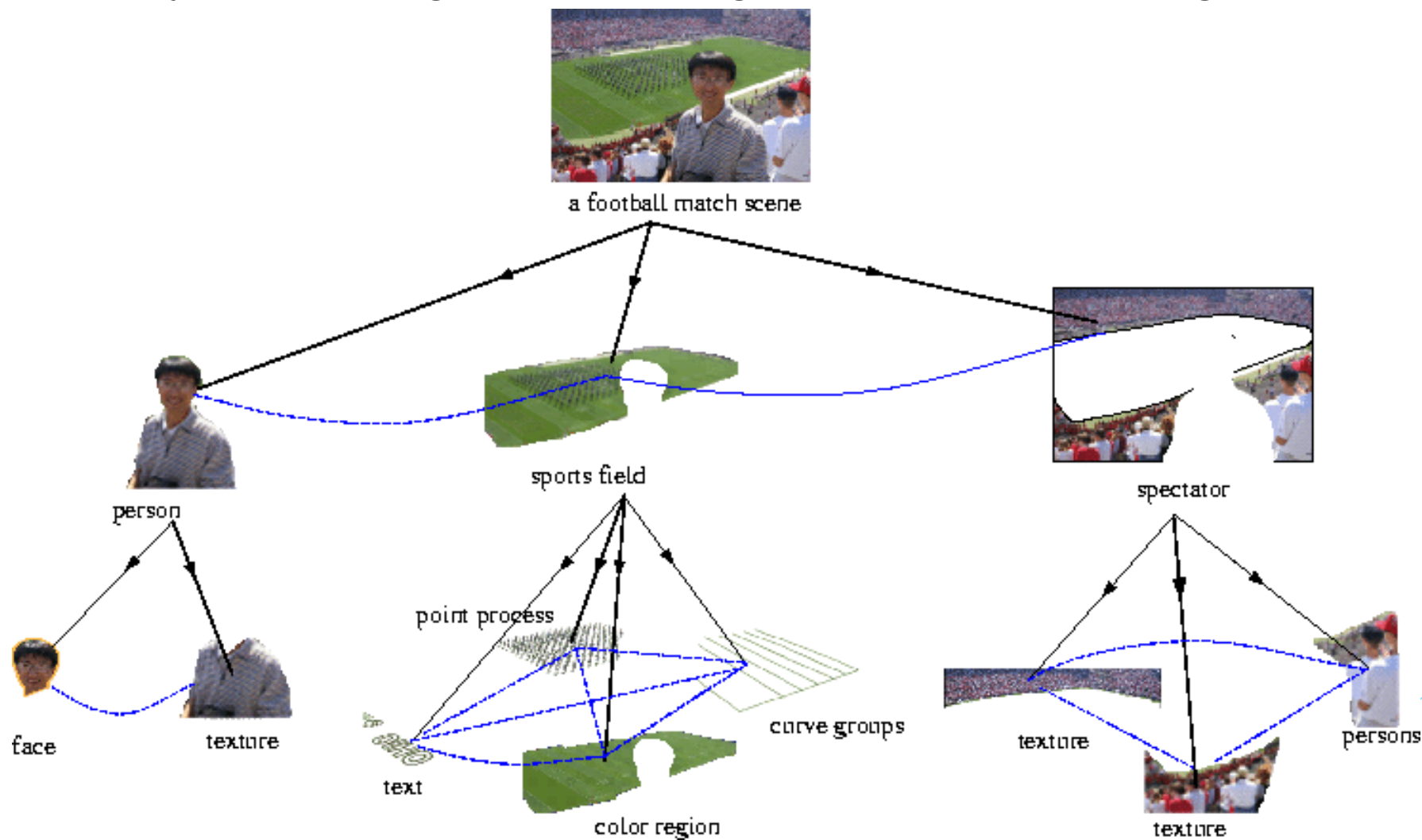


Probing of an image with a structuring element
(white and grey pixels have zero and non-zero values, respectively).

A morphological operation on a binary image creates a new binary image in which the pixel has a non-zero value only if the test is successful at that location in the input image.

Image Parsing

- The objective of image understanding is to parse an input image into its constituent patterns.



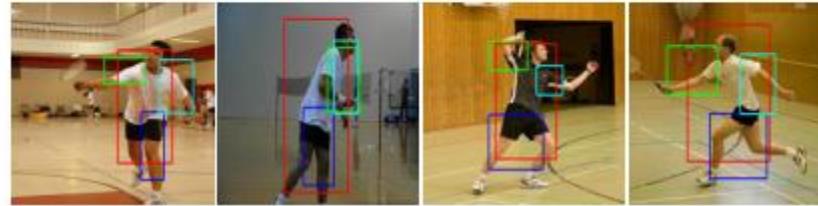
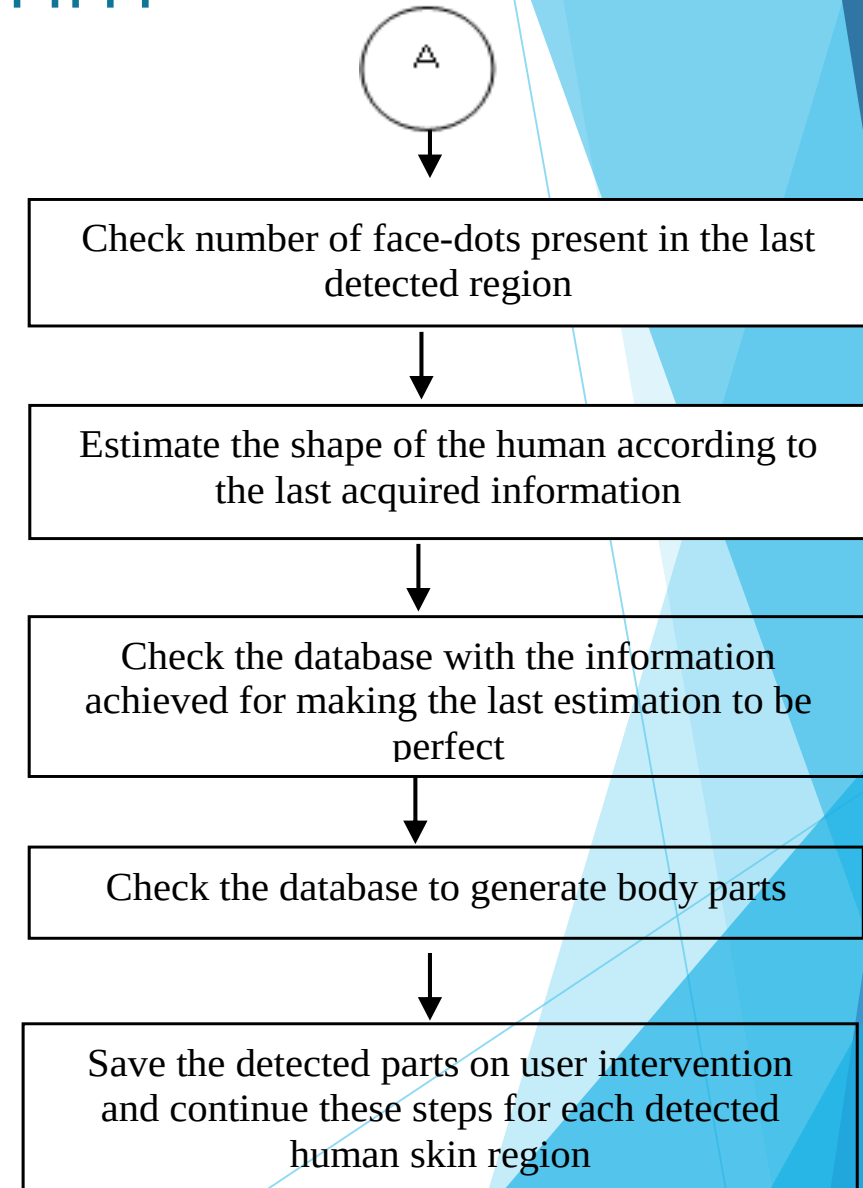
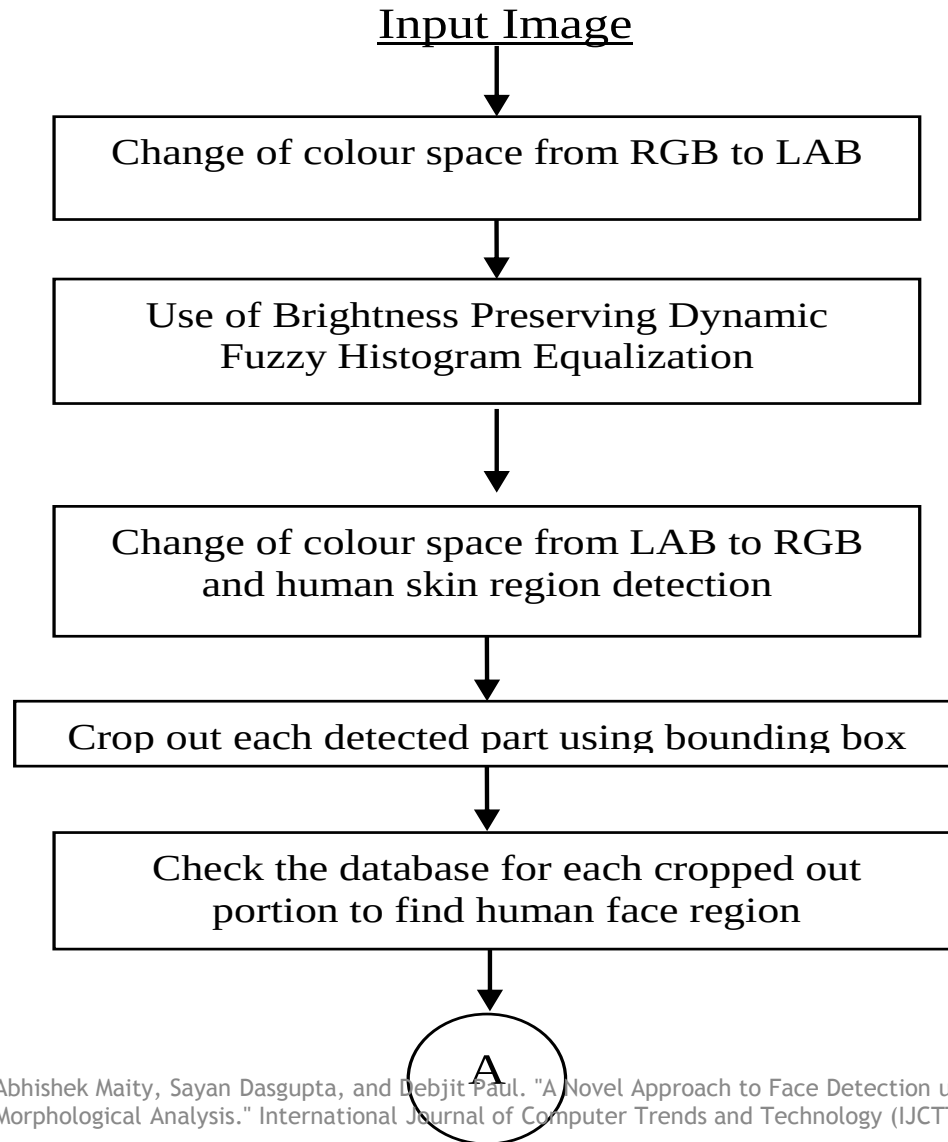
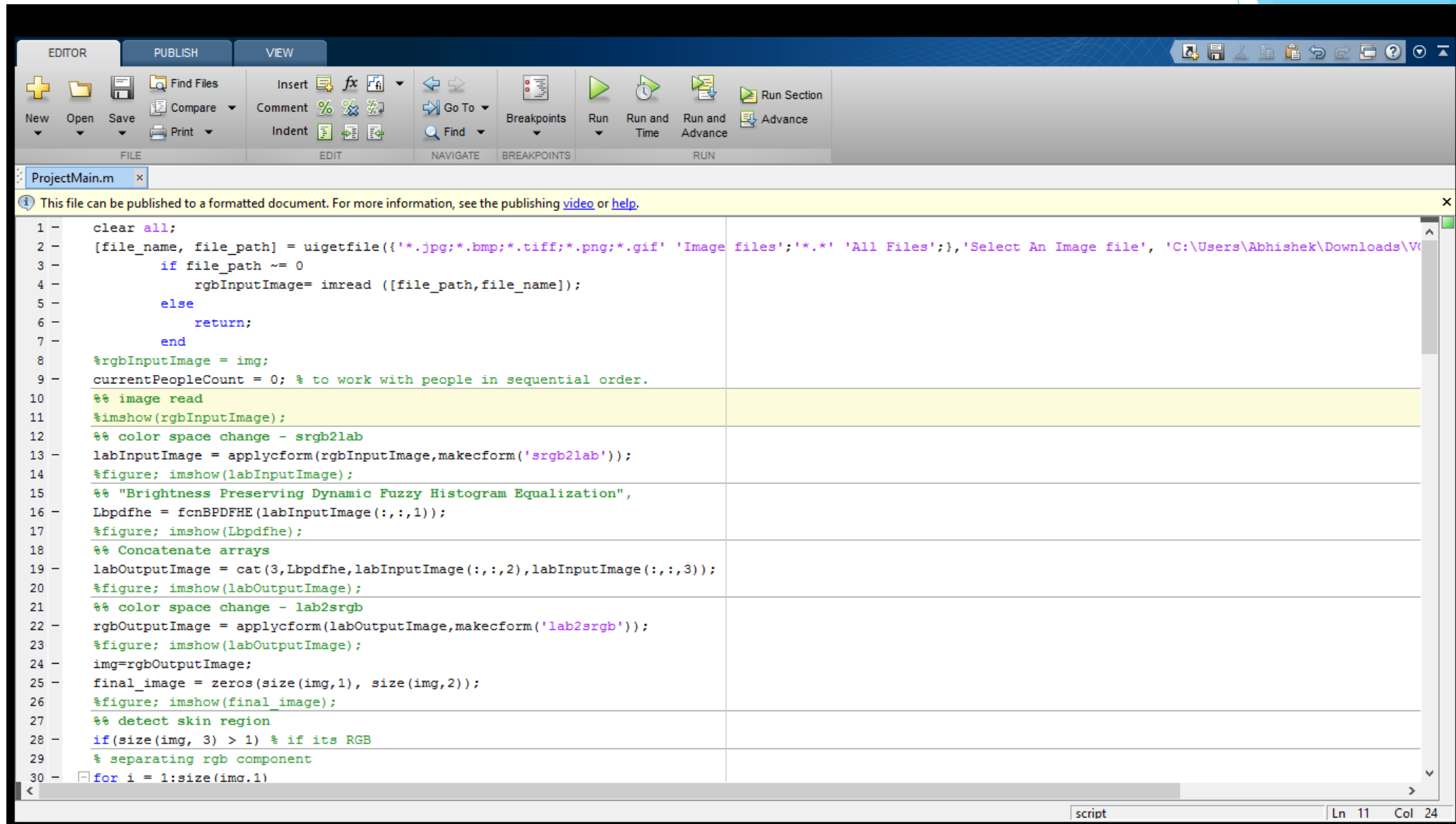


Figure 6: Examples of other information produced by our model. On each image, we show bounding boxes corresponding to the whole body, left arm, right arm and legs. The size of each bounding box is estimated from its corresponding poselet cluster.

Proposed Algorithm



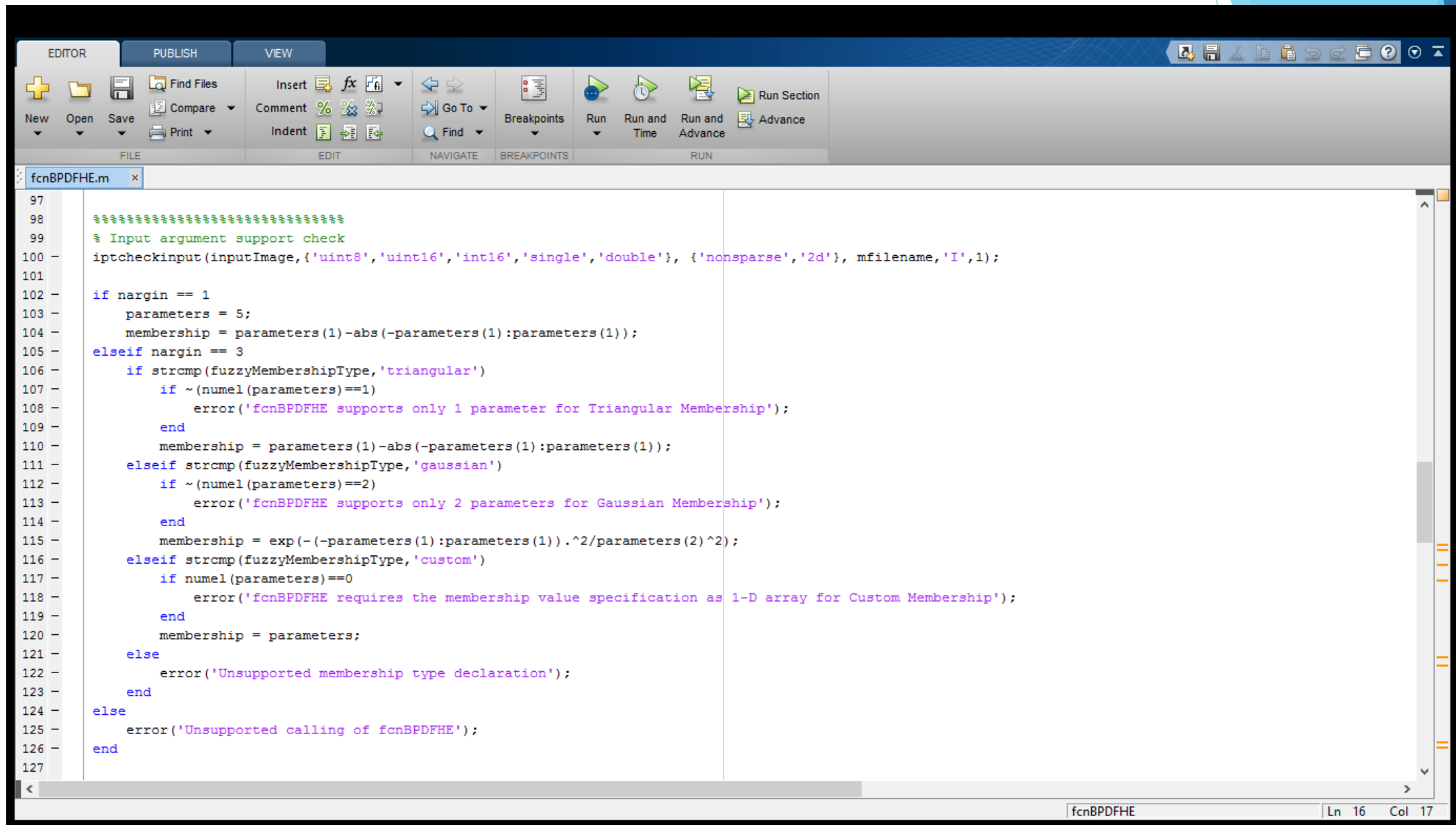
Code Snippet

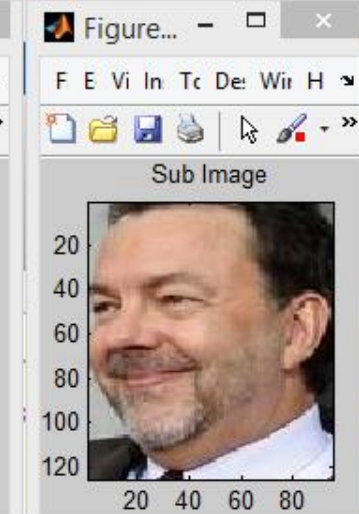
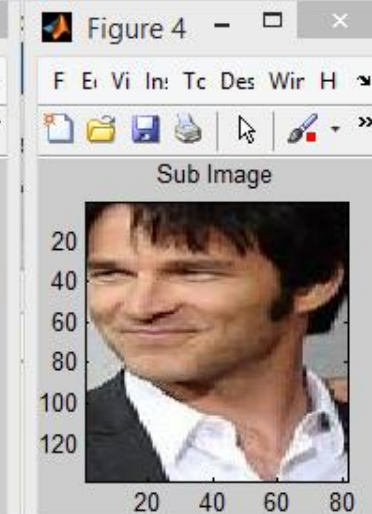
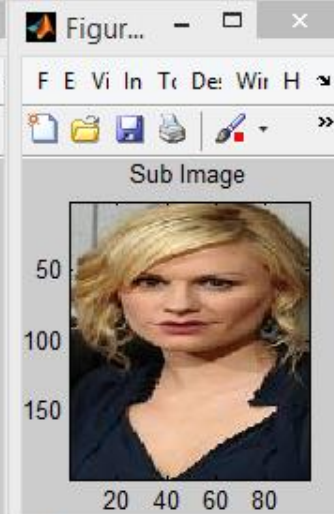
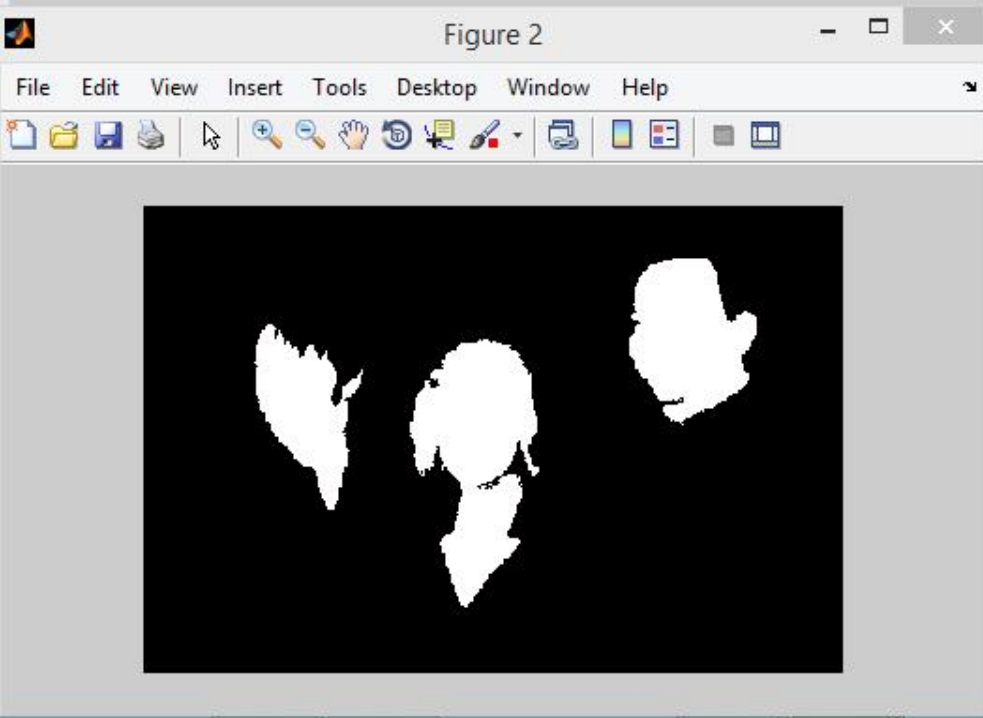
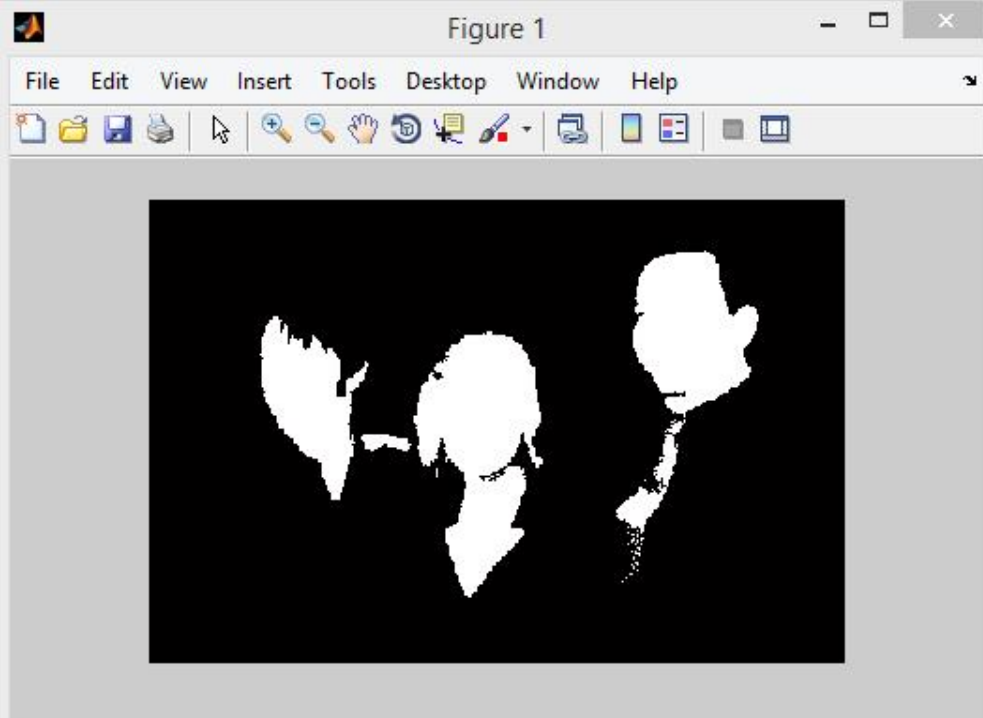


The image shows a MATLAB Editor window with a menu bar (EDITOR, PUBLISH, VIEW) and a toolbar with icons for file operations, editing, navigation, breakpoints, and running. The script in the editor is as follows:

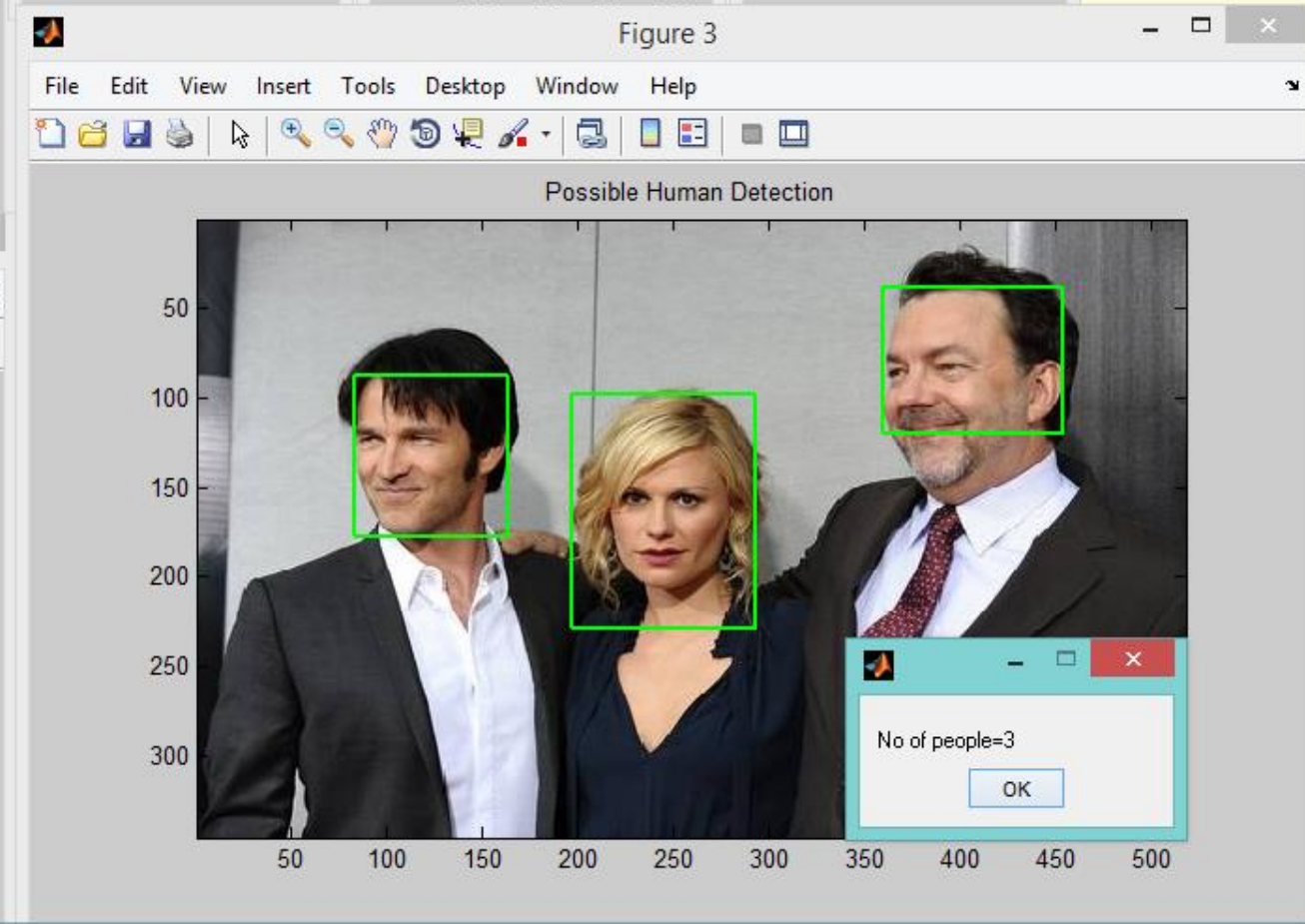
```
1 - clear all;
2 - [file_name, file_path] = uigetfile({'*.jpg;*.bmp;*.tiff;*.png;*.gif' 'Image files';'*..*' 'All Files';},'Select An Image file', 'C:\Users\Abhishek\Downloads\V
3 -     if file_path ~= 0
4 -         rgbInputImage= imread ([file_path,file_name]);
5 -     else
6 -         return;
7 -     end
8 - %rgbInputImage = img;
9 - currentPeopleCount = 0; % to work with people in sequential order.
10 - %% image read
11 - %imshow(rgbInputImage);
12 - %% color space change - srgb2lab
13 - labInputImage = applycform(rgbInputImage,makecform('srgb2lab'));
14 - %figure; imshow(labInputImage);
15 - %% "Brightness Preserving Dynamic Fuzzy Histogram Equalization",
16 - Lbpdfhe = fcnBPDFHE(labInputImage(:,:,1));
17 - %figure; imshow(Lbpdfhe);
18 - %% Concatenate arrays
19 - labOutputImage = cat(3,Lbpdfhe,labInputImage(:,:,2),labInputImage(:,:,3));
20 - %figure; imshow(labOutputImage);
21 - %% color space change - lab2srgb
22 - rgbOutputImage = applycform(labOutputImage,makecform('lab2srgb'));
23 - %figure; imshow(labOutputImage);
24 - img=rgbOutputImage;
25 - final_image = zeros(size(img,1), size(img,2));
26 - %figure; imshow(final_image);
27 - %% detect skin region
28 - if(size(img, 3) > 1) % if its RGB
29 -     % separating rgb component
30 -     for i = 1:size(img,1)
```

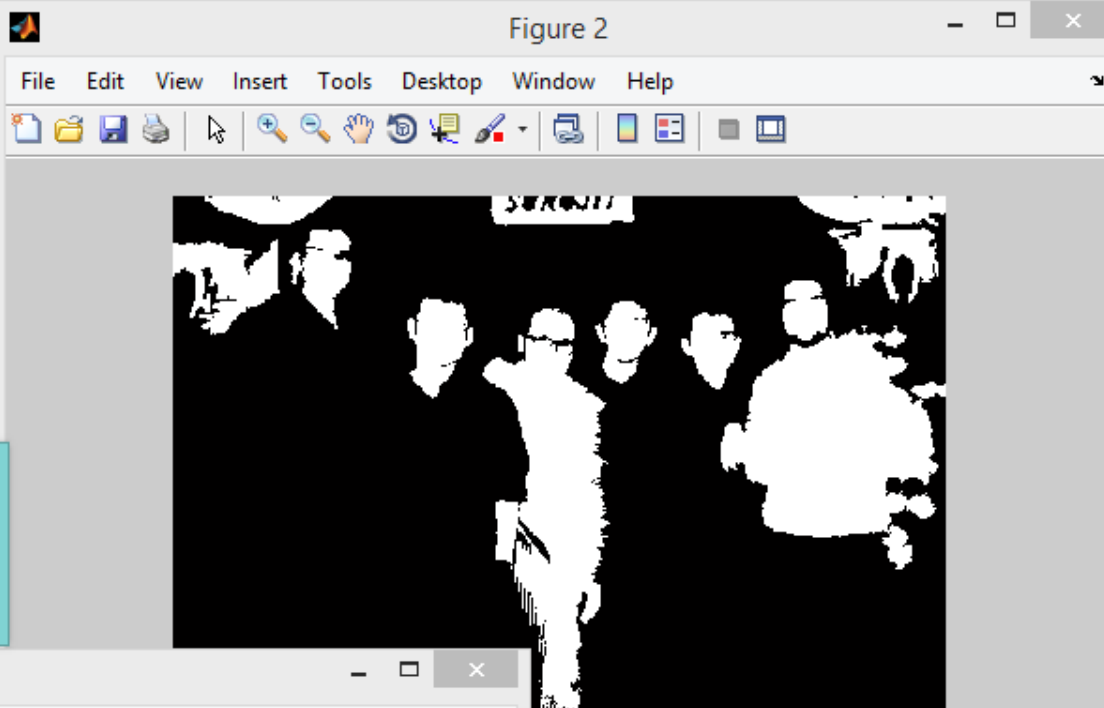
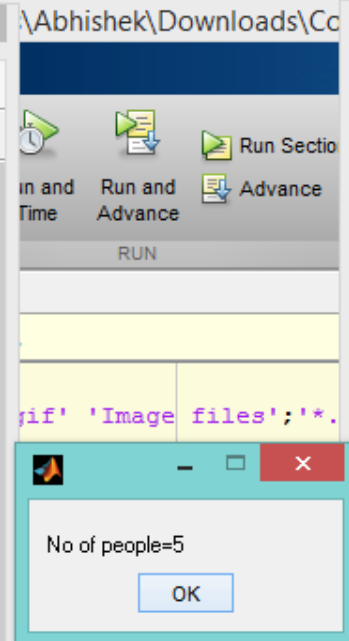
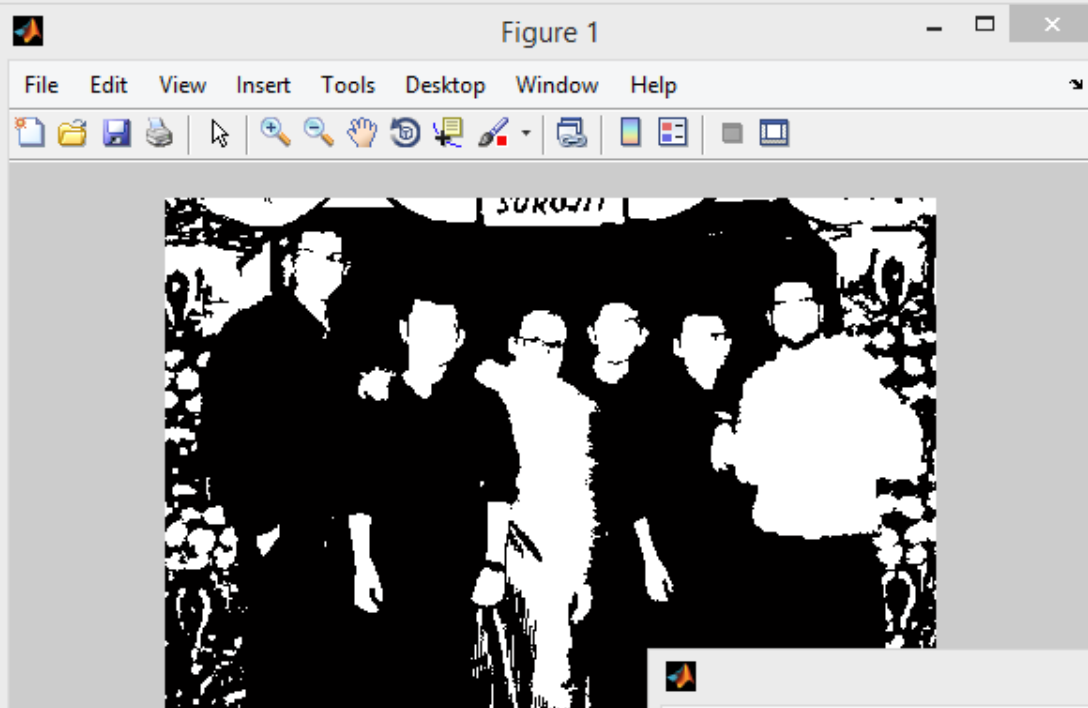
The status bar at the bottom indicates the current position is Ln 11, Col 24.





Successful
Detection





```

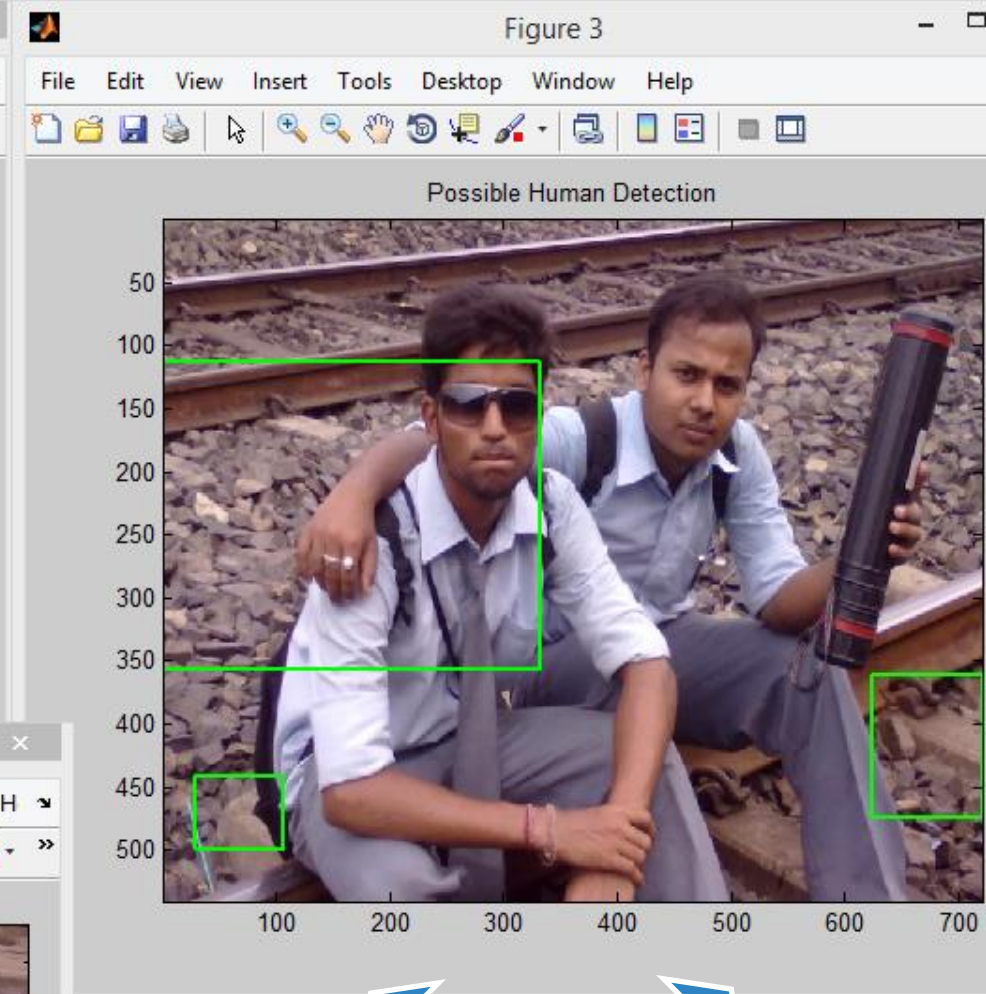
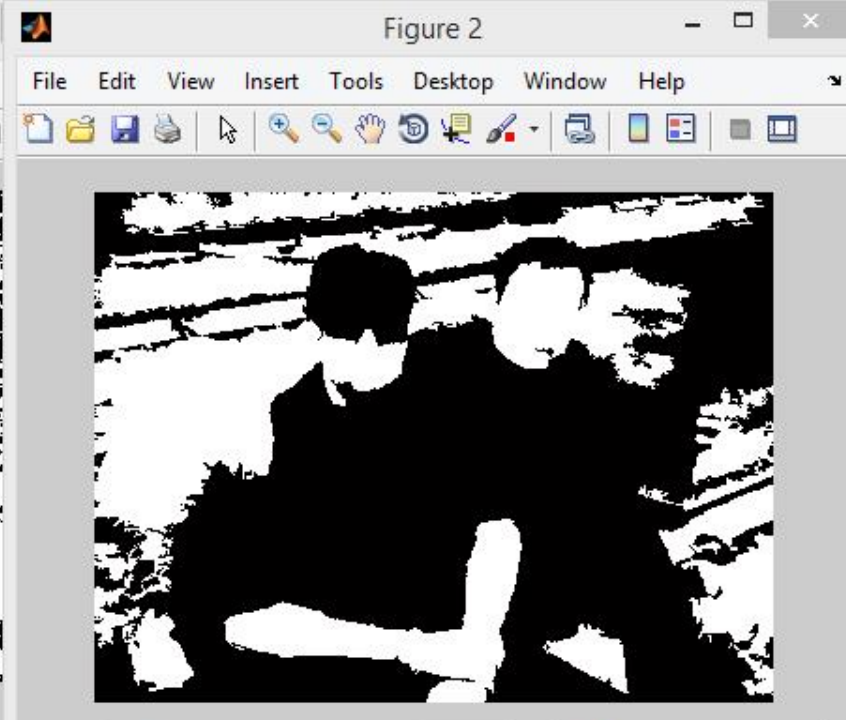
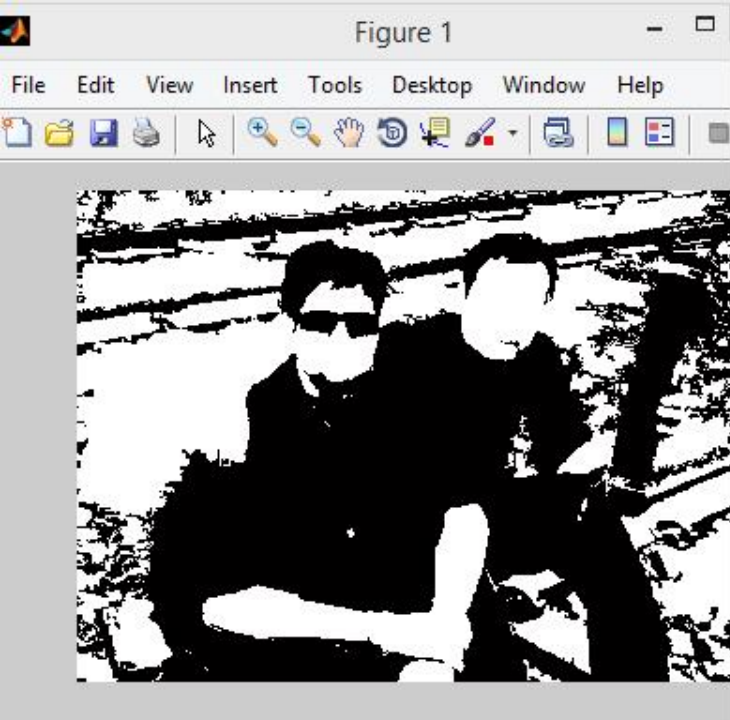
14 %figure; imshow(labInputImage);
15 %% "Brightness Preserving Dynamic
16 Lbpdfhe = fcnBPDFHE(labInputImage (
17 %figure; imshow(Lbpdfhe);
18 %% Concatenate arrays
19 labOutputImage = cat(3,Lbpdfhe,lab
20 %figure; imshow(labOutputImage);
21 %% color space change - lab2srgb
22 rgbOutputImage = applycform(labOut
23 %figure; imshow(labOutputImage);
24 img=rgbOutputImage;
25 final_image = zeros(size(img,1), s
26 %figure; imshow(final_image);
27 %% detect skin region
28 if(size(img, 3) > 1) % if its RGB
29 % separating rgb component
30 for i = 1:size(img,1)

```

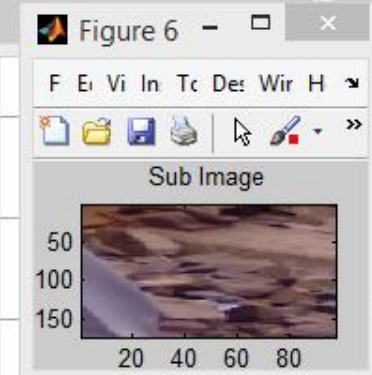
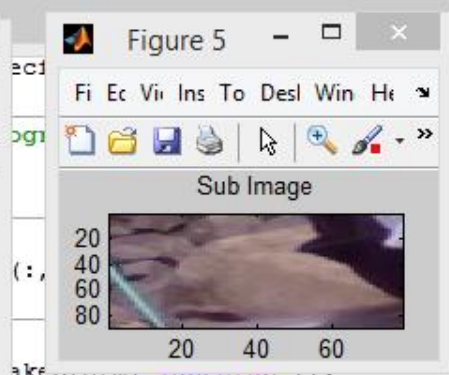
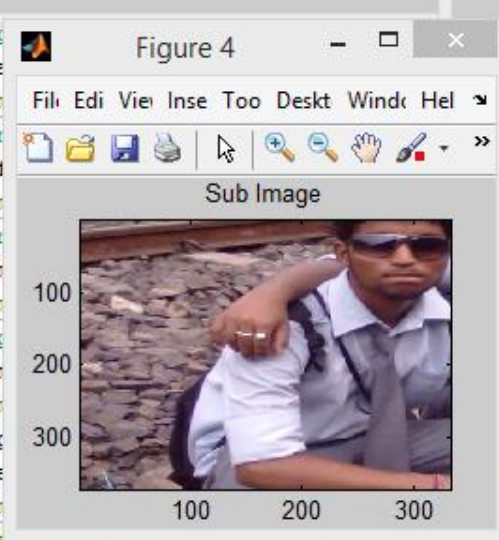


**Partial
Detection**

Ln 1 Col 1



```
12 %% color space
13 labInputImage = rgb2lab(rgbOutputImage);
14 %figure; imshow(labInputImage);
15 %% "Bright" thresholding
16 Lbpdfhe = 1;
17 %figure; imshow(labInputImage);
18 %% Concatenate
19 labOutputImage = [labInputImage; Lbpdfhe];
20 %figure; imshow(labOutputImage);
21 %% color space
22 rgbOutputImage = lab2rgb(labOutputImage);
23 %figure; imshow(rgbOutputImage);
24 img=rgbOutputImage;
25 final_image = img;
26 %figure; imshow(final_image);
27 %% detect skin region
28 if(size(img, 3) > 1) % if its RGB
29 % separating rgb component
30 for i = 1:size(img,1)
```



No of people=3
OK

Erroneous Human Detection



Result & Analysis

Accuracy η (in terms of percentage)

Where successful test files=16, total no. test files=21

$$\eta = \frac{\text{Successful test files}}{\text{Total no.of test files}} \times 100 = \mathbf{76.19\%}$$

- There has been a significant progress in the process of object identification in the input test image file.
- Humans can be extracted easily from a wide variety of objects from a set of images

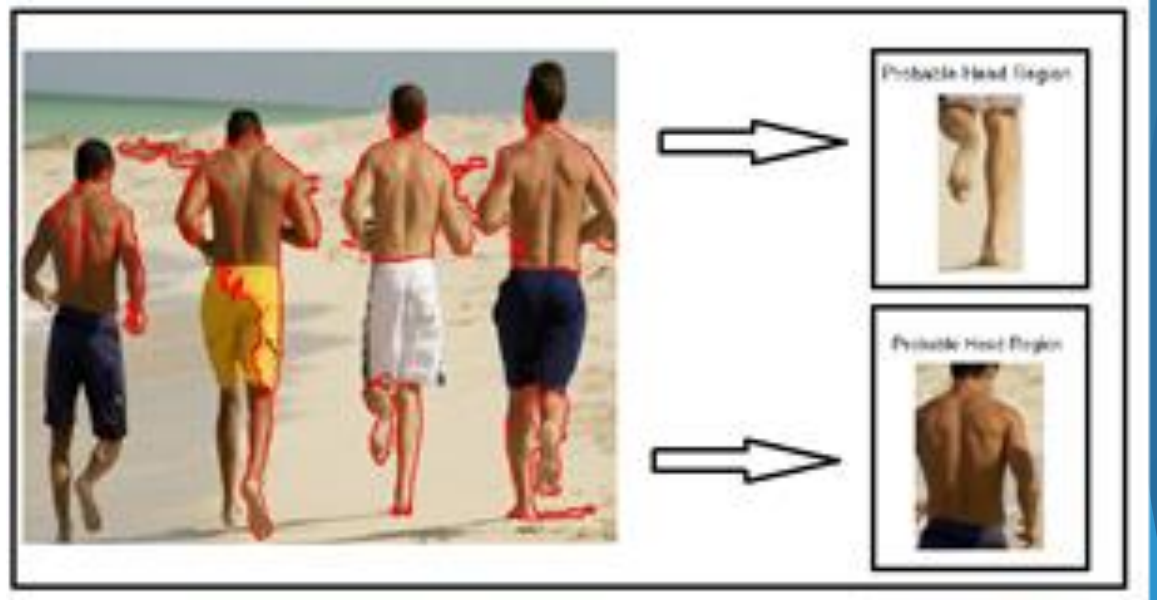
Limitations

- Full frontal face is necessary for the detection.
- The training has been done mainly on living organism. The training for the inanimate objects are yet to be incorporated into the system.
- Finally though since it is the field of image searching and recognition a hundred percent accurate output is not possible.

Future Scope

- Since we are working on the field of image searching and recognition a hundred percent accurate output is not possible.
- So in our future work we plan to improve on this accuracy. In this improvement work we plan to implement some more advanced features such as the Watershed algorithm, the SUSAN operator technique etc.

Now as we know a full frontal face is necessary to have. That means if there is a human present in an image and it is showing the back only then the above approach has to be modified [**Figure beside**]. Furthermore the training has been done mainly on human being, so in our future work we plan to train our system more accurately on other living organisms and non-living as well and even plan to incorporate the training of inanimate objects in our system.



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Thank You